

FLEX-6000 SIGNATURE SERIES SMARTSDR CAT SOFTWARE USER'S GUIDE

SmartSDR CAT version 3.0.19

25 April 2019

TABLE OF CONTENTS

1	INT	RODU	CTION	3
	1.1	D	escription of the SmartSDR CAT Interface	3
	1.2	O	perational Notes	3
2	SMA	RTSD	R CAT INSTALLATION MANAGEMENT	4
	2.1		martSDR CAT Installation Procedure	
	2.2	U	pgrading SmartSDR CAT	4
	2.3	R	emoving SmartSDR CAT	4
3	USIN	IG SM	ARTSDR CAT INTERFACE	7
	3.1	St	tarting the SmartSDR CAT Interface	7
		3.1.1	Auto Start Up	7
		3.1.2	Manual Start Up	7
	3.2	C	onfiguring SmartSDR CAT	7
		3.2.1	Main Window	8
		3.2.2	Port Edit Window	15
		3.2.3	Log Window	23
4	CAT	COM	MANDS	24
	4.1	Sı	upported CAT Commands	24
	4.2	Sı	upported Kenwood CAT Commands	25
	4.3	Fl	exRadio CAT Command Syntax Detail	26
	4.4	K	enwood CAT Command Syntax Detail	37
5	OTR	SP CO	MMANDS	45
	5.1	Sı	upported OTRSP Commands	45
6	WIN		R COMMANDS	
	6.1		upported Winkeyer Commands	
A	PPEN	IDIX A	: UNINSTALLING SMARTSDR CAT VERSIONS PRIOR TO V1.2.11	46
ΔΙ	PPFN	IDIY R	· KEY TERMS	47

1 INTRODUCTION

1.1 DESCRIPTION OF THE SMARTSDR CAT INTERFACE

The SmartSDR CAT interface bridges the legacy COM port interface used by many amateur radio systems to that of the FlexRadio Systems Signature Series radios. This allows third party programs such as loggers and digital mode clients that don't communicate directly with the radio using our Ethernet API to communicate without changes.

The FlexRadio CAT command set is based upon the Kenwood format. Therefore, any program that supports Kenwood models should work with our radio. In addition to the CAT protocol SmartSDR CAT also supports the Open Two Radio Switching Protocol (OTRSP) for SO2R automation, Winkeyer emulation, and PTT Port capabilities.

Because of the limitations in a legacy system like CAT, the SmartSDR CAT feature set is limited. Common features like tuning a VFO, transmitting, etc., are included. However, this means that many advanced features in a Signature Series radio will not be available via the CAT interface. Developers seeking additional access to such features should explore the API resources available at the <u>Flex Application Developer Program (ADP) web page</u>.

The Signature Series are a radio "server" platform that multiple "clients" can communicate with. SmartSDR for Windows is one such client and the SmartSDR CAT interface is a separate client, both of which can communicate concurrently with Signature Series radios.

1.2 OPERATIONAL NOTES

Most third-party CAT enabled programs are designed to control VFO A and possibly VFO B based on a 1 or 2 VFO legacy radio architecture.

With the Signature Series, the concept of a VFO maps very closely to a Slice Receiver. For this reason, a Slice Receiver Index (e.g. Slice A) is a required setup parameter for any protocol that utilizes the concept of a VFO. The selected Slice is *logically* mapped to the third-party CAT program's VFO A.

In the CAT protocol, the first time a split command such as 'FT1;' or 'ZZSW1;' is encountered, the SmartSDR CAT application will create a new "Split Slice" and set that Slice's Transmit flag (the typical Split configuration with a Signature Series Radio). This allows listening to either the receive and transmit frequencies or both. From that point forward, that Slice will be *logically* mapped to the third-party CAT program's VFO B. Commands that access VFO B information before one of the commands mentioned above is issued or after the Split Slice is manually closed will receive a "?;" response.

2 SmartSDR CAT INSTALLATION MANAGEMENT

The following sections describe how install, upgrade or remove SmartSDR CAT from your PC.

2.1 SMARTSDR CAT INSTALLATION PROCEDURE

During the installation of SmartSDR for Windows you may see the following informational dialog box as the FlexRadio Systems FlexVSP virtual serial port driver is installed. It may take a few minutes for the FlexVSP drivers to completely install. Please do not press the Cancel button if it appears that the installation has stopped as this will prevent SmartSDR CAT from operating properly.



When SmartSDR for Windows finishes installing and configuring the FlexRadio Systems FlexVSP software component, the new version of SmartSDR CAT will be started and an icon will be placed on the Desktop for easy subsequent starts.

2.2 UPGRADING SMARTSDR CAT

The SmartSDR CAT upgrade process is as simple as installing a newer version of SmartSDR for Windows. The installer will optionally include SmartSDR CAT and the virtual serial port driver (FlexRadio Systems FlexVSP), only upgrading required components when necessary.

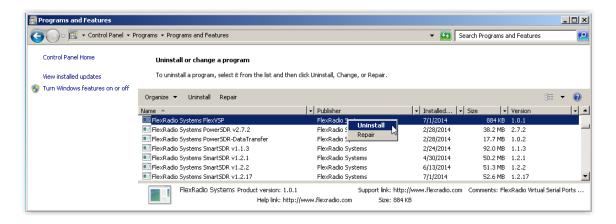
2.3 REMOVING SMARTSDR CAT

Note: If you have SmartSDR CAT v1.2.10 or earlier installed on your PC, see Appendix A.

The SmartSDR CAT application component is uninstalled automatically when you run the SmartSDR for Windows uninstaller. However, the virtual serial port driver, **FlexRadio Systems FlexVSP** must be uninstalled manually using the procedure described below. Note that it is not necessary to uninstall FlexVSP when upgrading SmartSDR and/or SmartSDR CAT.

CAUTION: Uninstalling the FlexRadio Systems FlexVSP driver without uninstalling the SmartSDR CAT application will result in an error when the SmartSDR CAT application is started. You should only uninstall the FlexRadio Systems FlexVSP driver when instructed to do so by upgrade instructions or by a FlexRadio System technical support engineer.

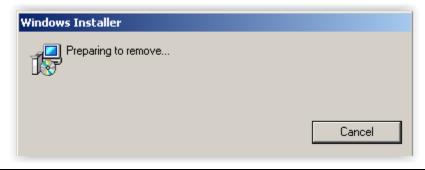
- 1. Close the **SmartSDR CAT** application.
- 2. Open the Windows Control Panel and select Uninstall a Program
- 3. Click on the **FlexRadio Systems FlexVSP** program entry.



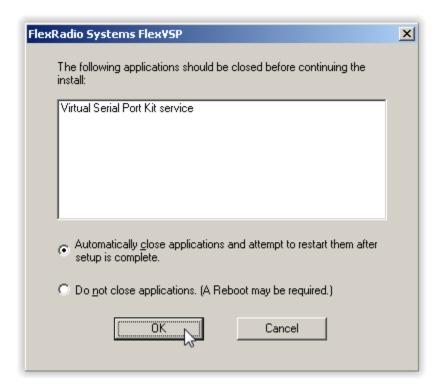
- 4. Click the **Uninstall** option above the list (or right click on the entry and select the **Uninstall** option).
- 5. Answer **Yes** to the prompt "Are you sure you want to uninstall FlexRadio Systems FlexVSP" as shown below.



6. The Windows Installer *Preparing to Remove* dialog box is displayed as shown below.



7. If you receive a prompt to "Automatically close applications and attempt to restart them after setup is complete", click on **OK** to continue. See image below.



8. A progress dialog box will be displayed as shown below as the FlexRadio Systems FlexVSP driver is being uninstalled.



9. After FlexVSP has finished uninstalling, manually reboot your PC if not prompted to do so.

3 USING SmartSDR CAT INTERFACE

3.1 STARTING THE SMARTSDR CAT INTERFACE

SmartSDR CAT is started by two methods described below. Usually SmartSDR CAT is started by the Auto Start Up method and is never closed, so it is always communicating with the configured FlexRadio Signature Series radio.

Note: SmartSDR CAT must be able to connect to a Signature Series radio to work properly.

3.1.1 Auto Start Up

SmartSDR CAT will start automatically when SmartSDR starts, if the **Autostart CAT** with SmartSDR option is selected in SmartSDR. When selected, SmartSDR CAT starts and stops with SmartSDR. If the SmartSDR CAT application window was minimized that last time it ran, it will start minimized when SmartSDR is restarted. It will remain running unless closed by the user. Clicking on the SmartSDR CAT icon will open the SmartSDR CAT User Interface for configuration.

3.1.2 Manual Start Up

You can manually start SmartSDR CAT by double clicking on the **SmartSDR CAT** program icon located on your Desktop or in the Windows Start Menu under the FlexRadio Systems program folder. If the application is already running, its window will appear.

3.2 CONFIGURING SMARTSDR CAT

When SmartSDR CAT starts the first time, it will create a Serial CAT port automatically at the lowest open port (COM4 or above) and a TCP CAT Port on port 5002.

If the FlexVSP driver is not loaded or has not fully started at the time the SmartSDR CAT user interface starts, an error message will be displayed. This condition in which the VSP driver has not fully started can exist on systems that utilize a solid state hard drive allowing Windows to run the Startup applications before the FlexVSP service has started. If this occurs, wait 15-30 seconds and then manually restart SmartSDR CAT.

3.2.1 Main Window

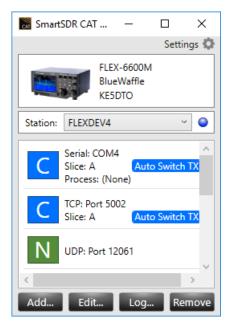


Figure 1 SmartSDR CAT Main Window

Near the top of the Main Window, an indicator shows whether SmartSDR CAT has connected to a radio and if it is using a SmartLink connection to a radio. Once a connection has been made, hovering the mouse cursor over this indicator will show the Model and Nickname (or Serial Number) of the connected radio. When no connection is present, this indicator will be shown as follows:



Figure 2 Main Window - Radio Not Connected

To select which radio to connect, click on the connection status box at the top of the window. It may also show a blue SmartLink indicator. This will bring up the radio chooser.

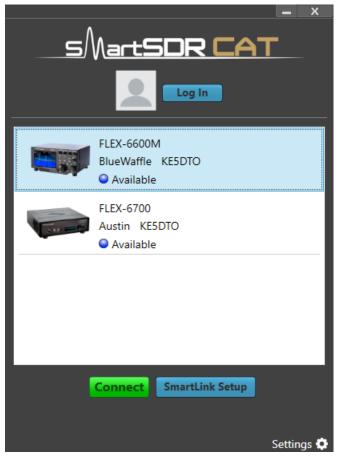


Figure 3 Radio Chooser

From this screen, the SmartLink Setup allows the user to verify the SmartLink settings and select a radio from the list. Once a radio is chosen, auto-connect settings are applied when starting up. These settings can be accessed by clicking on the settings icon in the SmartSDR CAT main window. Unchecking the **Auto Connect SmartLink** option will prevent automatically connecting to a remote radio which could cause unintended network bandwidth to be used.

Right clicking a radio in the radio chooser opens a menu selection that allows you to copy the detailed information about the selected radio to the clipboard, as shown below:



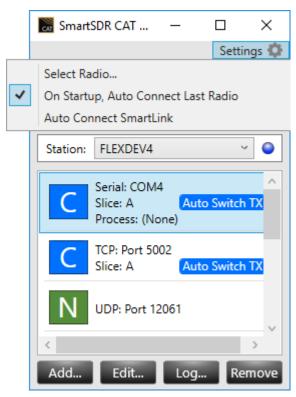


Figure 4 Auto Connect options

The **On Startup**, **Auto Connect Last Radio** option allow SmartSDR CAT to automatically connect to the last radio that was used if the radio is available on the network. The **Auto Connect SmartLink** does the same if the last radio was connected via SmartLink. This may not be desirable depending on bandwidth issues if operating remote via a mobile connection, for example.

The **Station** selection will initially show the last selected Station and an indication of whether that Station is currently connected to the Radio. The dropdown list will show any other Stations available on the connected radio. The Station selection is necessary to resolve which context to use when fielding CAT commands. For example, FA; asks what frequency Slice A is on. To answer this question, the Station must be known.

The Port list is the primary component of the Main Window. Each item in the list represents a single Port showing the relevant details of the port including the Protocol (CAT, OTRSP, PTT, or Winkeyer), the Port type (e.g. COM1 or TCP port 60000), and the associated Slice (A-H). The colored icon on the left side denotes the first letter of the protocol (C for CAT, O for OTRSP, etc.) Hover the mouse cursor over the indicator to display the Port Protocol.

NOTE:For Virtual Serial Port (VSP) pairs, only the Client side (the side to be used by the third-party application) of the VSP is shown in the Main Window.

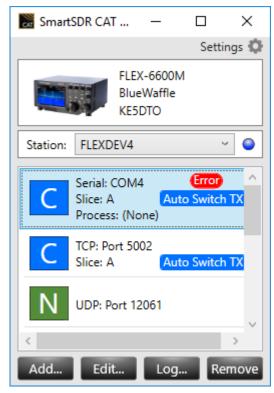


Figure 5 Main Window - Port Error

If there is a problem opening the Port (Serial or TCP), a red Error indicator will appear to the right of the Serial/TCP line. Hovering the mouse cursor over the error will produce a message that should help to shed some light on the source of the problem. If the Port is in conflict as a result of another program using it or if it is a hardware Serial port (perhaps a USB to Serial adapter) that is powered down or unplugged, simply closing the program, powering up the device and/or plugging the device in should resolve the problem. When the problem is resolved, the red Error indicator will disappear.

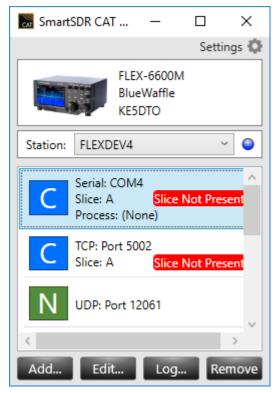


Figure 6 Main Window - Slice Not Present

If a Port's selected Slice is not found in the radio, a red indicator reading "Slice Not Present" will be shown. Creating a Slice using a Radio Client like SmartSDR for Windows will resolve this issue and cause the indicator to disappear.

The **Add** button allows the user to add an additional Port to the list. See the Port Edit Window description below for more information.

The **Edit** button allows the user to change Port settings. See the Port Edit Window description below for more information.

The **Log** button allows the user to open a diagnostic window. See the Log Window description below for more information.

The **Remove** button allows the user to remove a Port. Ctrl and Shift keys may be used to select multiple Ports for faster removal. Multiple selection does not apply to the Edit or Log buttons. Note that removing a FlexVSP Serial Port will result in those ports being removed from the system and may take several seconds to complete the device removal process. Right-clicking on the Remove button reveals a **Reset FlexVSP Port** option. Clicking this option will cause the system to remove all FlexVSP ports and then add back the pairs as defined in the Port list. This can help to recover a situation where the FlexVSP ports have been disassociated from the defined Ports.

To close the SmartSDR CAT application, click the red X in the upper right corner of the Main Window. A prompt to confirm avoids accidental disconnecting of all of the Ports with the radio.

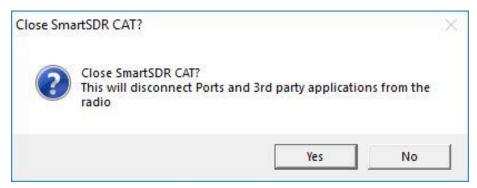


Figure 7 Close Dialog

3.2.2 Port Edit Window

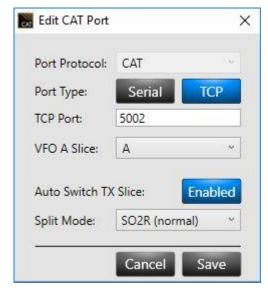


Figure 8 Port Edit Window

The Port Edit Window allows the user to set Port details when adding or editing a Port.

Before describing the various controls on this Window, it is appropriate to explain that the screenshots shown in the manual were taken in **Advanced mode**. To enable Advanced Mode, right click anywhere on the Port Edit Window and click the Advanced menu option.

Note: The screen image examples shown below are in Advanced Mode in order to display all of the possible options.

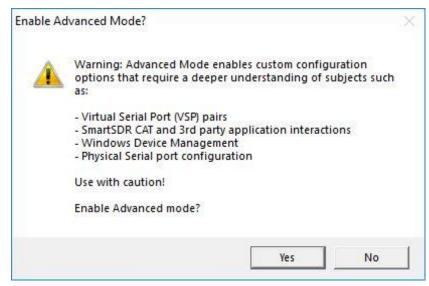


Figure 9 Advanced Mode Warning

A warning dialog as shown above will require confirmation that the user wants to use this mode. Using the Advanced Mode is not necessary for operation of SmartSDR CAT, but simply provides another degree of freedom in configuration for the Advanced user. In particular, when Advanced Mode is off, the CAT sides of VSP ports are not shown and the Serial Port to use for the Client side is chosen for the User. If any of this is confusing, leave Advanced Mode off.

The **Port Protocol** is the selected language of the Port. This can be CAT, OTRSP, PTT or Winkeyer. Note that while editing a Port, this field cannot be changed. To change the protocol on a Port, it is necessary to Remove the port from the Main Window and then set the new protocol when Adding the Port.

Protocol Descriptions:

CAT: Computer Aided Transceiver (CAT) was developed as a way to communicate with a radio through a serial interface. Commands are sent in text and are terminated with a semicolon. The command set varies depending on the transceiver make and model. The SmartSDR CAT implementation is based on the Kenwood command set including compatibility commands (2-character commands) and specialized FlexRadio specific commands (4-character commands beginning with ZZ).

Note: While the CAT protocol exposes many common radio operations, it is a dated interface and thus does not implement the entire set of features possible on a FlexRadio Signature Series radio. For more functionality and control, see the Flex Application Developer Program (ADP) web page.

OTRSP: The Open Two Radio Switching Protocol (OTRSP) was developed in order to facilitate and simplify Single Operator, 2 Radio (SO2R) configurations. Details on the protocol can be found here: http://www.klxm.org/OTRSP/.

PTT: The Push-To-Talk (PTT) protocol to enables serial port control of the Transmit mode. This allows for easy hardware configurations for triggering transmit.

Winkeyer: The Winkeyer port type emulates a subset of the Winkeyer functionality for easy integration with logging applications such as N1MM. The Winkeyer spec can be found here: http://klel.tripod.com/files/Winkey10.pdf.

The **Port Type** allows the Port to be setup for Serial or TCP connections. Note that PTT ports can only be setup in Serial mode.

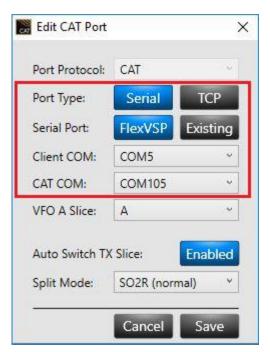


Figure 10 Serial FlexVSP Port Configuration

When **Serial** is selected, the Serial Port can be one of two types: FlexVSP or Existing.

A **FlexVSP** port will create a pair of Virtual Serial Ports (VSP) using the FlexVSP driver. One end of this pair is opened by the SmartSDR CAT application (the **CAT COM**) and the other end is opened by the 3rd party application (the **Client COM**). When creating or editing a FlexVSP Serial Port, note that it will take several seconds for the changes to take place due to delays in the driver.

When in Advanced Mode, when selecting a FlexVSP com port, all available or free com ports will be shown. This list is extensive since Windows can define up to 265 com ports.

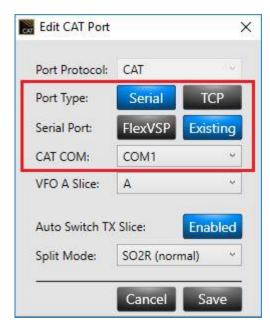


Figure 11 Serial Existing Port Configuration

When choosing an **Existing** Serial Port, the **CAT COM** specifies an existing COM port already present on the system. This is ideal for interfacing to hardware ports that speak the CAT language natively.

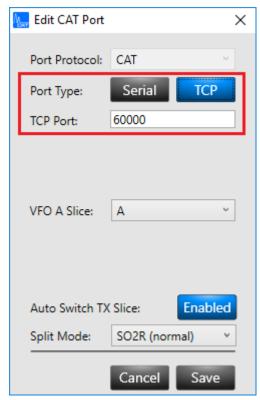


Figure 12 TCP Port Configuration

A **TCP** port requires only the TCP Port number to be specified. Connecting to this port will allow an application to communicate using the specified protocol (CAT, OTRSP, etc.) to the radio. Note that TCP is not available with the PTT protocol.

The **VFO A Slice** specifies which Slice will be used for the logical VFO A in the protocol. (not used with Winkeyer)

When enabled **Auto Switch TX Slice** automatically switches the Transmit Slice to the VFO A Slice selected above when a CAT TX command is sent on the com port. This feature allows multiple digital mode applications to operate at the same time on different VFO A Slice assigned slices by dynamically making the slice the transmit slice when the digital mode application is transmitting. If this option is not enabled, the operator will have to manually designate the Transmit Slice.

Note that PTT type ports will not show a VFO A Slice selection if this feature is disabled and the Main Window will show "TX" for the Slice.

The **Split Mode** determines whether a split Slice will be removed when coming out of Split mode (FT0; or ZZSW0; commands). In SO2R (normal) mode, the split Slice will be closed. In SO2V mode, the split Slice will be left open, allowing the user to continue using it in the typical VFO A/VFO B configuration. Note that going into Split mode (FT1;

or ZZSW1; commands) in either setting will still create a split Slice in the event that one is not already in place.

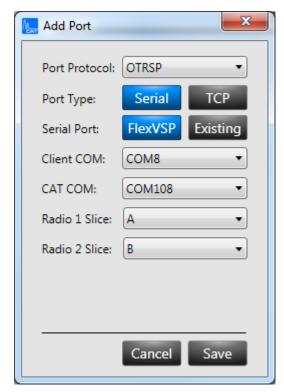


Figure 13 OTRSP Port Configuration

The OTRSP protocol has several unique fields.

The **Radio 1 Slice** is the Slice to be used when OTRSP commands reference the Radio 1 object. Similarly, **Radio 2 Slice** is the Slice to be used when OTRSP commands reference the Radio 2 object.

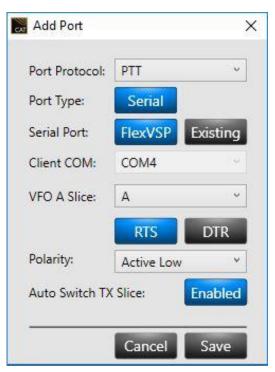


Figure 14 PTT Port Configuration

The PTT Protocol has several unique fields.

The **RTS** and **DTR** controls indicate whether to use the RTS or DTR Pins to signal PTT changes on the radio. Note that either or both of these can be used in a wired OR configuration (i.e. if both are enabled, then if either signal is asserted, PTT is signaled).

The **Polarity** indicates whether Transmit (PTT) should be active on a pin transition to Ground (Active Low) or when the pin is pulled up (Active High).

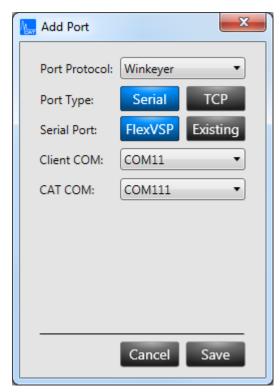


Figure 15 Winkeyer Port Configuration

The Winkeyer protocol has no unique fields.

The **Cancel** button will close the Window and cancel any changes on an Edit, or simply not execute an Add depending on how the Window was opened.

The **Save** button will execute any necessary changes to the Port on an Edit and will create the Port on an Add. Note that changes to the FlexVSP Serial Ports can take several seconds to complete.

3.2.3 Log Window

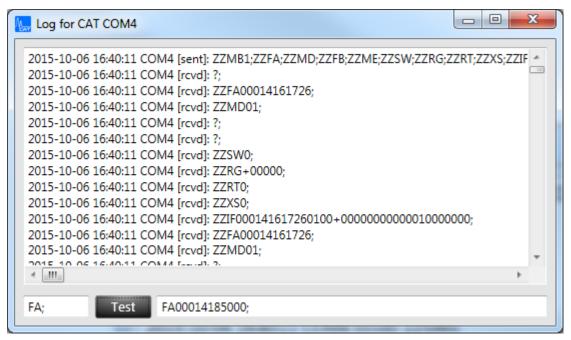


Figure 16 Log Window

The **Log Window** is primarily a diagnostic interface. It shows the stream of data being transferred across the Port in real time with date and timestamps to facilitate debugging of commands or connections. A test interface is also included that allows commands to be entered in the lower left Text Box. Commands can be executed by pressing Enter or by clicking on the Test button. The reply will be shown in the Text Box in the lower right corner.

Multiple Log Windows may be opened to view traffic on more than one port.

The traffic from all Ports is also logged to:

%appdata%\FlexRadio Systems\LogFiles\CAT.log for further debugging. Once a file grows larger than 5 Megabytes (MB), the file will be renamed CAT.log.1, then CAT.log.2, etc. and a new CAT.log will be created. A maximum of 5 log files are kept.

4 CAT COMMANDS

The following are the CAT commands supported in SmartSDR CAT. There are FlexRadio (ZZ) CAT commands and a subset of the Kenwood TS-2000 CAT command set for compatibility with older third-party CAT-enabled programs that do not support the FlexRadio CAT command set.

If a third-party CAT-enabled program does not have a FLEX-6000 or FlexRadio CAT option, then use the Kenwood TS-2000 configuration.

4.1 SUPPORTED CAT COMMANDS

- ZZAG Reads / Sets VFO A Audio Gain (0-100)
- ZZAI Auto Information State (on/off)
- ZZAR Reads / Sets VFO A AGC Threshold (0-100)
- ZZAS Reads / Sets VFO B AGC Threshold (0-100)
- ZZBI Reads / Sets Binaural RX State (On / Off)
- ZZDE Reads / Sets VFO A Diversity (DIV) state (On / Off) [FLEX-6700 only]
- ZZFA Reads / Sets VFO A Frequency (11 digit Hz)
- ZZFB Reads / Sets VFO B Frequency (11 digit Hz)
- ZZFI Reads / Sets VFO A DSP Filter Index
- ZZFJ Reads / Sets VFO B DSP Filter Index
- ZZFR Toggle VFO A/B Active
- ZZFT Toggle VFO A/B Transmit
- ZZGT Reads / Sets VFO A AGC Mode
- ZZIF Reads Transceiver Status
- ZZLB Reads / Sets VFO A Audio Pan (0-100, Left to Right)
- ZZLE Reads / Sets VFO B Audio Gain (0-100)
- ZZLF Reads / Sets VFO B Audio Pan (0-100, Left to Right)
- ZZMA Reads / Sets VFO A Mute (On / Off)
- ZZMD Reads / Sets VFO A DSP Mode
- ZZME Reads / Sets VFO B DSP Mode
- ZZMG Reads / Sets Transmitter Mic Gain (0-100)
- ZZNL Reads / Sets VFO A Wide Noise Blanker (WNB) Threshold (0-100)
- ZZNR Reads / Sets VFO A Noise Reduction (NR) State (On / Off)
- ZZPC Reads / Sets the RF Power Drive Level (0-100)
- ZZRC Clears RIT
- ZZRD Decrements RIT frequency
- ZZRG Reads / Sets VFO A RIT Frequency (+/- 5 digit Hz)
- ZZRT Reads / Sets VFO A RIT State (On / Off)
- ZZRU Increments the RIT frequency
- ZZRW Reads / Sets VFO B RIT Frequency (+/- 5 digit Hz)

- ZZRX Reads Receive State (On / Off) [inverse of MOX]
- ZZRY Reads / Sets VFO B RIT Frequency (+/- 5 digit Hz)
- ZZSM Read the S-Meter
- ZZSW Set Transmit VFO (0=A, 1=B)
- ZZTX Set MOX State (On / Off)
- ZZXC Clear XIT Frequency
- ZZXG Read / Set VFO A XIT Frequency (+/- 5 digit Hz)
- ZZXS Reads / Sets XIT State (On / Off)

4.2 SUPPORTED KENWOOD CAT COMMANDS

- AI Auto Information State (On / Off)
- FA Reads / Sets VFO A Frequency (11 digit Hz)
- FB Reads / Sets VFO B Frequency (11 digit Hz)
- FR Reads / Sets Active VFO (0=A, 1=B)
- FT Reads / Sets Transmit VFO (0=A, 1=B)
- GT Reads / Sets VFO A AGC Mode (0-Off, 2-Slow, 3-Medium, 4-Fast)
- ID Reads the transceiver ID number
- IF Reads Transceiver Status
- KS Reads / Sets CW Keyer Speed (5-100 WPM)
- KY Sends Text Morse Code
- MD Reads / Sets VFO A DSP Mode
- NB Reads / Sets VFO A Wide Noise Blanker State (On / Off)
- PC Reads / Sets RF Power Level (0-100)
- PT Reads / Sets CW Pitch Frequency (3 digit Hz)
- RC Clears RIT
- RD Decrements RIT frequency
- RT Reads / Sets VFO A RIT State (On / Off)
- RU Increments VFO A RIT Frequency
- RX Sets Receive State (TX Off)
- SH Reads / Sets VFO A Filter High Cut Frequency Index
- SL Reads / Sets VFO A Filter Low Cut Frequency Index
- SM Reads the S-Meter
- TX Sets Transmit State (On / Off)
- XT Reads / Sets VFO A XIT State (On / Off)

4.3 FLEXRADIO CAT COMMAND SYNTAX DETAIL

The following tables describe the FlexRadio CAT Command Syntax used with SmartSDR CAT.

ZZAG	ZZAG Sets or reads VFO A Audio Gain											
Get ZZAG ;												
Set	ZZAG	P1	P1	P1	;							
Answer ZZAG P1 P1 P1 ;												
Notes: P1 Values: Values 000 to 100.												

ZZAI	ZZAI Sets or reads the Auto Information mode for a Slice											
Get	ZZAI	• •										
Set	ZZAI	P1	;									
Answer	ZZAI	P1	;									

Notes: P1 = 0 Auto Information disabled, P1 = 1 Auto Information enabled. When enabled, CAT will actively send any frequency change (VFO A or B) formatted as an 'FA;' or 'FB;' response.

ZZAR	ZZAR Sets or reads VFO A AGC Threshold											
Get ZZAR ;												
Set	ZZAR	P1	P1	P1	;							
Answer ZZAR P1 P1 P1 ;												
Notes: P1 Values: Values 000 to 100.												

ZZAS	ZZAS Sets or reads VFO B AGC Threshold												
Get ZZAS ;													
Set	ZZAS	P1	P1	P1	;								
Answer	ZZAS	P1	P1	P1	;								

Notes: P1 Values: Values 000 to 100.

ZZBI	ZZBI Sets or reads Binaural Receive											
Get ZZBI ;												
Set	ZZBI	P1	;									
Answer	Answer ZZBI P1 ;											
Notes: P1 Values: $0 = Off$, $1 = On$												

ZZDE	Sets or reads Diversity (DIV) Button [FLEX-6700 ONLY]									
Get	ZZDE ;									
Set	ZZDE	P1	;							
Answer	Answer ZZDE P1 ;									
Notes: P1 Values: $0 = Off$, $1 = On$										

ZZFA	ZZFA Sets or reads VFO A Frequency												
Get	ZZFA	;											
Set	ZZFA	P1											
Set	ZZFA	P1	P1	P1	;								
Anguyan	ZZFA	P1											
Answer		P1	P1	P1	;								

Notes: P1 = frequency in Hz (11 digits). Blank digits must be filled with 0.

Example: 14.150.000 = 00014150000. May switch to 8 digit mode by doing an 8 digit set.

ZZFB	Sets or re	ads VFO	B Frequen	ісу								
Get	ZZFB	ZZFB ;										
Set	ZZFB	P1	P1	P1	P1	P1	P1	P1	P1			
		P1	P1	P1	;							
Answer	ZZFB	P1	P1	P1	P1	P1	P1	P1	P1			
		P1	P1	P1	;							

Notes: P1 = frequency in Hz (11 digits). Blank digits must be filled with 0.

Example: 14,150.000 = 00014150000. May switch to 8 digit mode by doing an 8 digit set.

ZZFI	ZZFI Sets or reads VFO A DSP Filter												
Get	ZZFI	;											
Set	ZZFI	P1	P1	;									
Answer	ZZFI	P1	P1	;									

Notes: P1 value represents a Filter index from 0 to 7 for decreasing bandwidth.

Example: If you are in LSB mode and your filter bandwidth is greater than 2.7K but less than or equal to 2.9K, ZZFI; will return 'ZZFI02;'. If your bandwidth were 2.901K, it would return 'ZZFI01;'.

ZZFJ	ZZFJ Sets or reads VFO B DSP Filter												
Get	ZZFJ	;											
Set	ZZFJ	P1	P1	;									
Answer	ZZFJ	P1	P1	;									

Notes: Similar to ZZFI for VFO B

ZZFR	Toggle V	FO A/B A	ctive			
Set	ZZFR	;				

Notes: If VFO B is not defined, this command just toggles VFO A Active on/off. Otherwise, if the radio is in "split mode" (ZZSW1) it will toggle between VFO A Active and VFO B Active.

ZZFT	Toggle V	FO A/B T	ransmit			
Set	ZZFT	;				

Notes: If VFO B is not defined, will just toggle VFO A Transmit on/off. Otherwise will toggle between VFO A Transmit and VFO B Transmit.

ZZGT	ZZGT Sets or reads VFO A AGC Mode									
Get	ZZGT	;								
Set	ZZGT	P1	;							
Answer	ZZGT	P1	;							

Notes: P1 Values: 0 = Off, 2 = Slow, 3 = Med, 4 = Fast

ZZIF	Γransceive	er status qu	ıery						
Get	ZZIF	;							
Answer	ZZIF	P1	P1	P1	P1	P1	P1	P1	P1
		P1	P1	P1	P2	P2	P2	P2	P3
		P3	P3	P3	P3	P3	P4	P5	P6
		P7	P7	P8	P9	P9	P10	P11	P12
		P13	P14	P14	P15	;			
Notes	P2 P3 P4 P5 P6 P7 P8 P9 P1 P1 P1 P1	(11 charache (4 charache (6 charache (1 charache (1 charache (2 charache (2 charache (2 charache (2 charache (2 charache (1 charache (2 ch	ters) Freq ters) RIT/ ter) RIT s ter) XIT s ter) Chan ter) Chan ter) MOX ter) Opera cter) VFC cter) Scar cter) VFC cter) CTC cter) CTC cters) Mo	uency step XIT frequ tatus. 0 = tatus. 0 = nel bank n nnel bank button sta ting mode Split statu Status. N Split stat CSS tone. re tone co t status. N	o size (000 ency (+nr off, 1 =	onnn or —n n. * on. * fot used, d Not used, off, 1 = on MD for se as FR. defaulted t as FT. defaulted ot used, defaulted tefaulted t	z/1000 = 5 innnn). * defaulted to defaulted a (transmit ettings. o 0. to 0. efaulted to o 0.	o 0. to 00. ting).	

ZZLB S	Sets or rea	ds VFO A	Audio Pa	ın						
Get ZZLB ;										
Set	ZZLB	P1	P1	P1	;					
Answer	ZZLB	P1	P1	P1	;					

Notes: P1 Values: Values 000 (full left) to 100 (full right).

ZZLE S	ZZLE Sets or reads VFO B Audio Gain										
Get ZZLE ;											
Set ZZLE P1 P1 P1 ;											
Answer	ZZLE	P1	P1	P1	;						
Notes: P	1 Values:	Values 0	00 to 100.								

ZZLF S	sets or rea	ds VFO B	Audio Pa	n						
Get ZZLF ;										
Set ZZLF P1 P1 ;										
Answer	ZZLF	P1	P1	P1	;					
Notes: P	1 Values:	Values 0	00 (full let	ft) to 100 ((full right)					

ZZMA Sets or reads VFO A Mute									
Get	ZZMA	;							
Set	ZZMA	P1	;						
Answer	ZZMA	P1	;						
Notes: P1	Notes: P1 Values: $0 = Off$, $1 = On$								

ZZMB	ZZMB Sets or reads VFO B Mute									
Get	ZZMB	;								
Set	ZZMB	P1	;							
Answer	ZZMB	P1	;							
Notes: P1	Notes: P1 Values: $0 = Off$, $1 = On$									

Get	ZZMD	;							
Set	ZZMD	P1	P1	;					
Answer	ZZMD	P1	P1	;					
P1 '	Values:								
	00	LSB							
	01	USB							
	03	CWL (Mode is C	CW, Lowe	r Sideband	d style tun	ing)		
	04	CWU (Mode is C	CW, Uppe	r Sideban	d style tun	ing)		
	05	FM							
	06	AM							
	07	DIGU							
	09	DIGL							
	10	SAM							
	11	NFM							
	12	DFM							
	20	FDV							
	30	RTTY	(ASKF –	requires t	hird-party	RTTY so	ftware)		
	40	DSTR	(D-STAR	requires '	ThumbDV	waveform	n and don	gle)	

ZZME	ME Sets or reads VFO B DSP Mode								
Get	ZZME	;							
Set	ZZME	P1	P1	;					
Answer	ZZME	P1	P1	;					
Notes: Se	e ZZMD	for values	•						

ZZMG	Sets or re	Sets or reads the Transmitter Mic Gain Level										
Get	ZZMG	ZMG ;										
Set	ZZMG	P1	P1	P1	;							
Answer	ZZMG	ZMG P1 P1 ;										
	4 7 7 1											

Notes: P1 Values: Values 000 to 100.

ZZNL	Sets or re	ads VFO	A Wide N	oise Blank	ker (WNB) Level			
Get	ZZNL	;	- T TYTGO TY		ler () / I (B	Lever			
Set	ZZNL	P1	P1	P1	;				
Answer	ZZNL	P1	P1	P1	;				
Notes: P	1 Values:	Values 0	00 to 100.	1	1		L	1	
ZZNR	Sets or res	ads Slice N	Joise Red	uction (NI	2) State				
Get	ZZNR	;	Voise Real						
Set	ZZNR	P1	;						
Answer	ZZNR	P1	;						
		0 = Off							
110103. 1	1 varaes.	0 – 011,							
ZZPA	Sets the P	anadapter	data IP A	ddress:Po	rt				
Set	ZZPC	<ip></ip>	:	<port></port>					
					•		•		
ZZPC	Sets or rea	ads RF Po	wer Drive	Level					
Get	ZZPC	;							
Set	ZZPC	P1	P1	P1	;				
Answer	ZZPC	P1	P1	P1	;				
Notes: P	1 Values:	000 to 10	00		1			1	
ZZPE	Sets whetl	her the Pa	nadapter d	lata is Ena	bled				
Set	ZZPE	P1	;						
		0 = Disabl		ı nabled	<u> </u>			<u> </u>	
		~	,						
	G1 G1								
ZZRC	1	ce A RIT	Frequency	/ 				T	
Set	ZZRC	;							
Notes: Se	ets the RIT	Frequenc	cy to zero.						

ZZRD	Decrement the RIT frequency										
Set	ZZRD	ZZRD P1 P1 P1 P1 ;									
Set	ZZRD	;									

Notes: ZZRD without parameter P1 will decrement the RIT frequency 10 Hz in CW, DIGU, and DIGL modes; 50 Hz in USB, LSB, and AM modes. P1 (00000 to 99999) will decrement the VFO A RIT Frequency by the amount entered.

ZZRG	Sets or re	Sets or reads VFO A RIT Frequency										
Get	ZZRG	ZZRG ;										
Set	ZZRG	ZRG P1 P2 P2 P2 P2 ;										
Answer	ZZRG	ZZRG P1 P2 P2 P2 P2 ;										
Notes: P1	otes: P1 = Polarity (+ or -) P2 = 00000 to 99999											

ZZRT	Sets or reads VFO A RIT State										
Get	ZZRT	ZZRT ;									
Set	ZZRT	P1	;								
Answer	ZZRT	P1	;								

Notes: P1: 1 = On, 0 = Off.

ZZRU	Incremen	Increment VFO A RIT frequency										
Set	ZZRU	ZRU P1 P1 P1 P1 ;										
Set	ZZRU	;										

Notes: ZZRU without parameter P1 will increment the RIT frequency 10 Hz in CW, DIGU, and DIGL modes; 50 Hz in USB, LSB, and AM modes. P1 (00000 to 99999) will increment the VFO A RIT Frequency by the amount entered.

ZZRW	Sets or re	Sets or reads VFO B RIT Frequency									
Get	ZZRW	ZRW ;									
Set	ZZRW	P1	P2	P2	P2	P2	P2	;			
Answer	ZZRW	RW P1 P2 P2 P2 P2 ;									

Notes: P1 = Polarity (+ or -) P2 = 00000 to 99999

ZZRX	ZZRX Sets or reads the Receive state (can only set to RX)										
Get ZZRX ;											
Set	t ZZRX 1 ;										
Answer	Answer ZZRX P1 ;										
Notes: P	Notes: P1 Answer Values: $0 = Off$, $1 = On$. 'ZZRX0;' is not supported.										

ZZRY	Sets or re	Sets or reads VFO B RIT State									
Get	ZZRY	ZZRY ;									
Set	ZZRY	ZZRY P1 ;									
Answer	ZZRY	P1	;								
Notes: P1	Totes: P1: $1 = On, 0 = Off.$										

ZZSM	Read the S-Meter									
Get	ZZSM	ZZSM ;								
Answer	ZZSM	P1	P1	P1	;					

This command will read the S-Meter value for the slice that is assigned to the CAT port P1 = 000 to 260

ZZSM reads the received signal strength in dBm where S9 = -73 dBm. The range is -140 dBm to -10 dBm with a scale factor of 2 (P2 max = 260). The actual signal strength, in dBm, is the value of ZZSM divided by 2 minus 140.

ZZSW	Sets or re	eads the T	ransmit Fl	ag (VFO	A or B)						
Get	ZZSW	ZSW ;									
Set	ZZSW	P1	;								
Answer	ZZSW	P1	;								

Notes: P1 = 0 VFO A Transmit flag is set, P1 = 1 VFO B Transmit flag is set. If VFO B has not been created, and ZZSW1; is sent, VFO B will be created near VFO A. Note that logical VFO B is not necessarily Slice B, and could be any Slice depending on which Slices already exist. The Split Slice will be shown on the Main Window on the Slice line for the Port when one is defined. The Split Slice will be removed (if it exists) when processing the ZZSW0; command.

ZZTX	Sets or reads Transmit State (MOX)								
Get	ZZTX	;							

Set	ZZTX	P1	;						
Answer	ZZTX	P1	;						
Notes: P1 = 0 Radio is in receive mode P1 = 1 Radio is in transmit mode									

ZZXC	Clear VF	O A XIT	Frequency	/						
Set	ZZXC	ZZXC ;								
Notes: Se	ets the XIT	frequenc	y to zero.							

ZZXG	Sets or re	Sets or reads VFO A XIT Frequency										
Get	ZZXG	XG ;										
Set	ZZXG	P1	P2	P2	P2	P2	P2	;				
Answer	ZZXG	G P1 P2 P2 P2 P2 ;										

Notes: P1 = Polarity (+ or -) P2 = 00000 to 99999

ZZXS	ZZXS Sets or reads VFO A XIT State									
Get ZZXS ;										
Set	ZZXS	P1	;							
Answer ZZXS P1 ;										

Notes: P1: 0 = Off, 1 = On.

4.4 KENWOOD CAT COMMAND SYNTAX DETAIL

The following tables describe the Kenwood CAT Command Syntax used with SmartSDR CAT

AI Sets	AI Sets or reads the Auto Information mode										
Get	Get AI ;										
Set	AI	P1	;								
Answer	Answer AI P1 ;										

Notes: P1 = 0 Auto Information disabled, P1 = 1 Auto Information enabled. When enabled, CAT will actively send any frequency change (VFO A or B) formatted as an 'FA;' or 'FB;' response.

AG Se	AG Sets or reads VFO A Audio Gain										
Get	AG ;										
Set	AG	AG P1 P1 ;									
Answer	AG	P1	P1	P1	;						
Notes	Notes $P1 = 000 \text{ to } 100.$										

FA Set	s or reads	Slice A fi	requency						
Get	FA	;							
Cat	FA	P1	P1	P1	P1	P1	P1	P1	P1
Set	ГА	P1	P1	P1	:				
Angruan	FA	P1	P1	P1	P1	P1	P1	P1	P1
Answer	ΓA	P1	P1	P1	;				

Notes: P1 = frequency in Hz (11 digits). Blank digits must be filled with 0.

Example: 14,150.000 = 00014150000. May switch to 8 digit mode by doing an 8 digit set.

FB Se	ts or reads	Slice B f	requency						
Get	FB	;							
Set	FB	P1	P1	P1	P1	P1	P1	P1	P1
		P1	P1	P1	;				
Answer	FB	P1	P1	P1	P1	P1	P1	P1	P1
		P1	P1	P1	;				

Notes: P1 = frequency in Hz (11 digits). Blank digits must be filled with 0.

Example: 14,150.000 = 00014150000. May switch to 8 digit mode by doing an 8 digit set.

FR Set	FR Sets or reads VFO A/B Active flags									
Get	Get FR ;									
Set	FR	P1	;							
Answer	nswer FR P1 ;									

Notes: P1 will be "0" when VFO A Active flag is set. P1 will be "1" when VFO B Active flag is set. Setting 'FR1;' without VFO B will result in ';'

FT Set	FT Sets or reads VFO A/B Transmit flags								
Get FT ;									
Set	FT	P1	;						
Answer	Answer FT P1 ;								

Notes: P1 = "0" sets VFO A Transmit flag. P1 = "1" sets VFO B Transmit flag. If VFO B has not been created, and FT1; is sent, VFO B will be created near VFO A. Note that logical VFO B is not necessarily Slice B, and could be any Slice depending on which Slices already exist. The Split Slice will be shown on the Main Window on the Slice line for the Port when one is defined. The Split Slice will be removed (if it exists) when processing the FT0; command.

GT Set	GT Sets or reads VFO A AGC Mode									
Get GT ;										
Set	GT	P1	P1	P1	;					
Answer	Answer GT P1 P1 ;									

Notes: P1 Values: 000 = Off, 002 = Slow, 003 = Med, 004 = Fast

ID Reads the transceiver ID number										
Get ID ;										
Answer	Answer ID P1 P1 ;									

Notes: P1 Values: 904 = Flex-6700, 905 = Flex-6500, 906 = Flex-6700R, 907=Flex-6300

IF Tra	nsceiver st	tatus query	/						
Get	IF	;							
Answer	IF	P1	P1	P1	P1	P1	P1	P1	P1
		P1	P1	P1	P2	P2	P2	P2	Р3
		P3	Р3	P3	P3	P3	P4	P5	P6
		P7	P7	P8	P9	P10	P11	P12	P13
		P14	P14	P15	;				
Notes	P2 P3 P4 P5 P6 P7 P8 P9 P1 P1 P1	(11 charac (4 charac (6 charac (1 ch	ters) Frequency (ters) RIT/ster) RIT ster) XIT ster) Channeter) Channeter) MOX ter) Operater) VFC cter) Scanceter) VFC cter) CTC cter) Mo	uency step XIT frequ tatus. 0 = tatus. 0 = nel bank n nel bank status button stating mode Split status Split status Split status SS tone. re tone co	o size (000 ency (+nm off, 1 = o off, 1 = o umber. No number. No ex. See MI us. Same lot used, dus. Same Not used, ntrols. No	onnn or —n n. fot used, d Not used, off, 1 = on for settin as FR. defaulted t defaulted ot used, defaulted ot used, defaulted	z/1000 = 5 znnnn). defaulted to defaulted a (transmittings. to 0. to 0. efaulted to	o 0. to 00. ting).	

KS Set	KS Sets or reads the CW keying speed										
Get	KS	KS ;									
Set	KS	S P1 P1 ;									
Answer	KS	P1	P1	P1	;						
Notes	P1 = 005 to 100.										

KY Se	KY Sends text to CWX for conversion to Morse												
Get KY ;													
Set	KY	P1	P2										
		P2											
		P2											
		P2	;										
Answer	KY	P1	;										

Notes: P1 = character buffer available; 0=YES/1=NO (SmartSDR is not buffer limited so P1 will always return a "0". P2 = Any of the 56 printable ASCII characters. Empty character positions in P2 must contain a space. SmartSDR CAT will accept the Kenwood protocol as shown above but it is not limited to the same strict formatting. The number of P2 characters is limited to 256.

MD Se	Sets or reads VFO A DSP mode										
Get	MD	;									
Set	MD	P1	;								
Answer	MD	P1	;								
Notes	P1 = 1	LSB									
	2	USB									
	3	CW									
	4	FM (NFN	M, DFM, I	FDV)							
	5	AM (SA)	M)								
	6	DIGL (R	DIGL (RTTY)								
	9	DIGU									

NB Set	NB Sets or reads VFO A Wide Noise Blanker (WNB)									
Get NB ;										
Set	Set NB P1 ;									
Answer	NB	P1	;							
Notes: P	Notes: P1 $0 = Off$, $1 = On$									

PC Sets or reads the RF Power Drive Level									
Get PC ;									
Set PC P1 P1 ;									
Answer	PC	P1	P1	P1	;				
Notes: P1 Values: 000 to 100									

PT Set	PT Sets or reads the CW Pitch Frequency									
Get	PT	;								
Set PT P1 P1 ;										
Answer	PT	P1	P1	P1	;					
Notes: P1 Values: 000 to 999										

RC Clear VFO A RIT Frequency									
Set	RC	;							
Notes: Se	ets the RIT	frequenc	y to zero.						

RD Decrement VFO A RIT Frequency									
Set	RD	P1	P1	P1	P1	P1	;		

Notes: RD without parameter P1 will decrement the RIT frequency 10 Hz in CW, DIGU, and DIGL modes; 50 Hz in USB, LSB, and AM modes. P1 (00000 to 99999) will decrement the VFO A RIT Frequency by the amount entered.

RT Sets or reads VFO A XIT State									
Get	RT	;							
Set	RT	P1	;						
Answer RT P1 ;									

Notes: P1: 0 = Off, 1 = On.

RU Increment VFO A RIT frequency									
Set	RU	P1	P1	P1	P1	P1	;		

Notes: RU without parameter P1 will increment the RIT frequency 10 Hz in CW, DIGU, and DIGL modes; 50 Hz in USB, LSB, and AM modes. P1 (00000 to 99999) will increment the VFO A RIT Frequency by the amount entered.

RX Se	RX Sets Receive mode										
Set	RX	;									
Notes: R	Notes: RX is a write only command.										

SH Sets	s or reads	VFO A D	SP Filter l	High Cut I	ndex			
Get	SH	;						
Set	SH	P1	P1	;				
Answer	SH	P1	P1	;				
Notes	LSB/US	B/CW/DI	GU/DIGL	,	AM	[
		00 = 1	400		2500)		
		01 = 1	600		3000)		
		02 = 1	800		4000)		
		03 = 2	000		5000)		
		04 = 2	200					
		05 = 2	400					
		06 = 2	600					
		07 = 2	800					
		08 = 3	000					
		09 = 3	400					
		10 = 4	000					
		11 = 5	000					

SL Sets	or reads	VFO A D	SP Filter I	Low Cut In	ıdex		
Get	SL	;					
Set	SL	P1	P1	;			
Answer	SL	P1	P1	;			
Notes	LSB/US	B/CW/DI	GU/DIGL	,	AM		
		00 = 0			0		
		01 = 5	0		100		
		02 = 1	00		200		
		03 = 2	00		500		
		04 = 3	00				
		05 = 4	00				
		06 = 5	00				
		07 = 6	00				
		08 = 7	00				
		09 = 8	00				
		10 = 9	00				
		11 = 1	000				

SM Reads VFO A S-Meter								
Get	SM	;						
Answer	SM	P2	P2	P2	P2	;		

This command will read the S-Meter value for the slice that is assigned to the CAT port

Notes: Read-only

P1 = 0, P2 = 0000 - 0030

Reads S9 approximately equal to 0015. Use ZZSM if possible.

TX Sets Transmit Mode (MOX)									
Set	TX	P1	P1	;					
Note: TX is a write only command.									

XT Sets or reads XIT State							
Get	XT	;					
Set	XT	P1	;				
Answer	XT	P1	;				
Notes: P1: $1 = On, 2 = Off.$							

5 OTRSP COMMANDS

The following are the OTRSP commands supported in SmartSDR CAT. The full OTRSP command set can be found here: http://www.k1xm.org/OTRSP/.

5.1 SUPPORTED OTRSP COMMANDS

RX1 Connect Radio 1 to both headphones
RX2 Connect Radio 2 to both headphones
RX1S Connect Radio 1 to Left, Radio 2 to Right (focus Radio 1)
RX2S Connect Radio 1 to Left, Radio 2 to Right (focus Radio 2)
RX1R Connect Radio 1 to Right, Radio 2 to Left (focus Radio 1)
RX2R Connect Radio 1 to Right, Radio 2 to Left (focus Radio 2)
TX1 Set Radio 1 as the transmitter
TX2 Set Radio 2 as the transmitter

6 WINKEYER COMMANDS

The following are the Winkeyer commands supported in SmartSDR CAT. The full Winkeyer command set can be found here: http://klel.tripod.com/files/Winkey10.pdf.

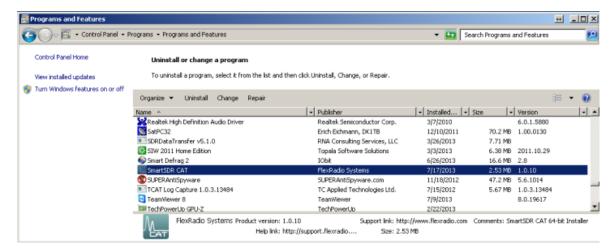
6.1 SUPPORTED WINKEYER COMMANDS

- <0x00> Admin Command
- <0x02> Set CW sending speed
- <0x08> Backup input pointer (backspace)
- <0x0A> Clear input buffer
- <0x0F> Load Defaults (speed only)
- <0x1C> Buffered Speed Change (implemented as immediate for now)

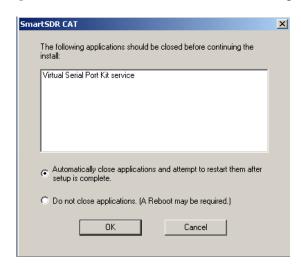
APPENDIX A: Uninstalling SmartSDR CAT versions prior to v1.2.11

THIS PROCEDURE IS NOT REQUIRED IF YOU HAVE INSTALLED SMARTSDR V1.2.17 OR GREATER

- 1. Close the **SmartSDR CAT** application and any programs that connect to the FLEX-6000 via CAT. This includes DDUtil.
- 2. Open the Windows Control Panel and select Uninstall a Program
- 3. Look for the **SmartSDR CAT**, **CAT_32** or **CAT_64** program entries and right click on them to display the Uninstall menu



- 4. Left click on the Uninstall option.
- 5. Answer **Yes** to the prompt "Are you sure you want to uninstall SmartSDR CAT"
- 6. SmartSDR CAT will begin to uninstall.
- 7. If you receive a prompt to "Automatically close applications and attempt to restart them after setup is complete", click on **OK** to continue. See image below.



8. After SmartSDR CAT has finished uninstalling, reboot your PC.

APPENDIX B: KEY TERMS

The following table provides definitions for terms relevant to this document.

Term	Definition		
AGC	Automatic Gain Control		
CAT	Computer Assisted Transceiver		
DSP	Digital Signal Processing		
LAN	Local Area Network		
MOX	Manually Operated switch		
NR	Noise Reduction		
OTRSP	Open Two Radio Switching Protocol		
PA	Power Amplifier		
RIT	Receiver Incremental Tuning		
RX Receive or Receiver			
SO2R	Single Operator, 2 radios		
TCP/IP	Transmission Control Protocol / Internet Protocol		
XIT	transmitter Incremental Tuning		
TX	Transmit or Transmitter		
VFO Variable Frequency Oscillator			